



- ports F4Pro**
- S1 B00
 - S2 B01
 - S3 A03
 - S4 A02
 - S5 A01
 - S6 A08

- B01: MOTOR1 OUT S1
- B02: MOTOR2 OUT S2
- A03: SERVO1 OUT S3 (PITCH / ELEV)
- A02: SERVO2 OUT S4 (ROLL / AIL1)
- A01: SERVO4 OUT S5 (ROLL / AIL2)
- A08: SERVO4 OUT S6 (YAW / RUD)

```
# motor mixer
mmix 0 1.000 0.000 0.000 0.000
mmix 1 1.000 0.000 0.000 0.000
```

```
# servo mix
smix 0 3 0 100 0
smix 1 4 0 100 0
smix 2 5 2 100 0
smix 3 2 1 100 0
```

Video Transmitter TRAMP HV (5.8GHZ)

FC – OMNIBUS F4Pro V3

- TM32 F405, BARO: BMP280
- gyro/acc sensor: MPU6000

FIRMWARE

- BetaFlight 4.0.2
- RunCam Robin
- Video Transmitter TRAMP HV 5.8 GHz
- Video Receiver RC700D (diversity)
- GPS Modul u-blox NEO6M or BN880, BN280
- SPEKTRUM Receiver 4649T 2.4 GHz
- SPEKTRUM Transmitter 8G2
- (ESC DYS Aria 35A 32bit – BL_Heli32)
- (BEC FOXY UBEC 5V/3A)
- (MOTOR 2627-1950kv)

GPS/MAG modul BN880

J10 - UART 6 + 3

